

1           **Embedded 3D Printing of Isotropically Enhanced Lattice Structure with**  
2           **Programmable Elasticity *via* Three-Dimensional Fiber Alignment**

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22   **Abstract:**

23   Engineered composites with fiber orientation in a complete three-dimensional (3D) context are  
24   highly desired for maximizing structural performance as they mimic the well-organized fiber  
25   arrangement in natural composites. However, most fabrication techniques lack the capability for  
26   through-plane (z-axis) alignment, limiting the possibility for structural design and performance  
27   optimization. In this study, we present an embedded 3D printing approach that enables complete  
28   3D fiber alignment, including region-specific alignment control along the through-plane direction.  
29   Our method utilizes the extrusion and suspension of composite inks within a supporting matrix.  
30   By regionally adjusting the ink extrusion rate and nozzle translation rate, we locally manipulated  
31   the fiber arrangement within the composite 3D architecture. We demonstrate that the 3D alignment  
32   of carbon fibers in a structural composite significantly enhances both mechanical properties and  
33   thermal conductivity in the in-plane and through-plane directions. Furthermore, by strategically  
34   arranging regional fiber orientations within micro-architected materials, we fabricated  
35   metamaterial engineered composites with programmable anisotropy ratio and directional moduli.

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38   **Teaser**

39   Embedding 3D aligned fiber in Herschel-Bulkley gel enables metamaterial with new design space  
40   in thermal-mechanical properties.

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45   **MAIN TEXT**

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## 2 **1. Introduction**

3 Anisotropic structures, including fibers, platelets, and rods, are a defining characteristic of  
4 composite materials. (1–5). Natural composites, such as nacre and bamboo, show that 3D  
5 oriented reinforcing fibers not only provide exceptional properties such as high stiffness in all  
6 directions, but also tailor the material’s mechanical behavior at specific regions for diverse natural  
7 environments (6, 7). The oriented fibers/platelets can also create shorter pathways for electron  
8 mobility to achieve much better thermal and electrical conductivity, which is highly desired for  
9 electronics, batteries, packaging applications etc. (8–10) Researchers have developed engineered  
10 composites that possess the oriented fibers and architected matrices, such as stacked woven  
11 carbon fiber fabrics of reinforced polymer (CFRP) composites exhibiting excellent mechanical  
12 strength and lightweight properties (11, 12), and short carbon fiber reinforced matrices with  
13 significantly enhanced thermal conductivity for fast heat dissipation (13, 14). Recent advances in  
14 additive manufacturing (AM) have unlocked new possibilities for engineered composites, offering  
15 unprecedented design freedoms through the creation of complex three-dimensional architectures  
16 (15–18). Through the deliberate design of 3D micro-architectures enabled by 3D printing,  
17 composites exhibit metamaterial-like behaviors, such as high-strength and stiffness at a fraction of  
18 their solid counterparts, impact resistance, negative Poisson ratio, as well as self-sensing and shape  
19 morphing.

20 Despite advances, fiber arrangement within the matrix often remains stochastic, limiting the  
21 tunability and optimization of composite properties. Recent efforts have been made to incorporate  
22 meso-scale control of particulate orientations in 3D printed matrices to address the challenge. In  
23 the extrusion-based printing process, a shear field generated during resin extrusion induces fiber  
24 alignment along the printing path, enabling the coupling of fiber arrangement with the printed 3D  
25 geometry by tuning the extrusion rate and printing speed (19, 20). For example, researchers have  
26 developed techniques that control the velocity ratio, defined as extrusion rate over nozzle moving  
27 speed, to tune the carbon fiber alignment (21). Other fillers, such as cellulose fiber, graphene,  
28 boron nitride and others, have also been oriented in designed directions and regions within various  
29 thermoplastic and thermoset matrices by fused deposition modeling (FDM) and direct ink writing  
30 (DIW) (22–30). Due to the layer-by-layer deposition process intrinsic to extrusion based printing,  
31 fibers are typically aligned in the x-y plane, while through-plane (z-axis) alignment remains a  
32 challenge but is crucial for achieving fully optimized three-dimensional properties. External fields,  
33 such as an acoustic field and a magnetic field, have been applied to the liquid resin vat in digital  
34 light processing (DLP) to achieve through-plane fiber orientation (31–33). These methods,  
35 however, are restricted to fibers that respond to external fields(34). More critically, the fields were  
36 applied uniformly to the entire vat, resulting in a single, uniform fiber orientation throughout the  
37 material, regardless of location. This uniformity limits the ability to tune the fiber alignment  
38 differently at specific locations in both in-plane and through-plane directions, thereby significantly  
39 restricting the design space for creating complex 3D fiber architectures. One significant drawback  
40 is the anisotropic nature of the resulting properties, where the strengthening in certain directions  
41 comes at the expense of weakened properties in others. By contrast, the excellent properties of  
42 natural composites originate from the well-arranged fiber alignment in any 3D directions at any  
43 3D locations. Researchers have also developed curved-slicing coupled with multi-DOF robotic  
44 arms to offer through-plane extrusion capability (35, 36). However, this method is limited to  
45 thermoplastics, as the extruded material needs to be rigid enough to support overhang structures,  
46 and only small angles of Z-direction alignment can be achieved due to the gravitational force

1 exceeding the material's strength. Other methods to achieve the through-plane fiber orientation  
2 include applying rotational nozzles which control the fiber alignment in the through-plane  
3 rotational direction by tuning the rotation speed (37). However, the achieved alignment is still  
4 limited to the pre-determined rotational directions, lacking full z-directional freedom.

5 Here, we present an embedded 3D (EMB3D) printing method that achieves comprehensive particle  
6 alignment control simultaneously in both the through-plane and in-plane directions. Unlike prior  
7 approaches limited to regional or fixed through-plane fiber orientations, our technique achieves  
8 full 3D control, allowing fiber alignment in any direction at various points of ink deposition, which  
9 leads to significant property improvement in a complete three-dimensional context. By  
10 individually planning extrusion paths in any 3D directions, this method facilitates precise fiber  
11 alignment in arbitrary 3D orientations, with independent control at specific locations both within  
12 and beyond the x-y plane. Such a level of 3D alignment control surpasses the previously reported  
13 methods. Moreover, the synergistic control of fiber alignment and macroscopic architecture design  
14 allows the creation of engineered metamaterial composites with highly programmable properties.  
15 While carbon fiber (CF) serves as the reinforcing component in our method, our approach can be  
16 extended to numerous other anisotropic structures orientations, offering versatile functional  
17 properties across diverse areas.

## 18 19 **2. Materials and methods**

### 20 **2.1 Composite ink and supporting matrix**

21 The ink is composed of a base resin (bisphenol A diglycidyl ether, DGEBA, Sigma Aldrich), a  
22 reactive diluent (neopentyl glycol diglycidyl ether, DGENG, Sigma Aldrich), a curing agent (2-  
23 ethyl-4-methylimidazole, Sigma Aldrich), a rheology modifier (fumed silica, CAB-O-SIL TS720,  
24 Cabot), and a reinforcing filler carbon fiber (CF, milled carbon fiber, PC 100, E&L Enterprise, Inc,  
25 7  $\mu\text{m}$  in diameter, 120  $\mu\text{m}$  mean length). The mass ratio of DGEBA : DGENG is 1 : 1, and the  
26 loading of curing agent, TS 720, CF in regard to the total mass of DGEBA and DGENG is 10 wt%,  
27 8 wt%, and 40 wt%, respectively. To prepare the ink, the mixing was done in a planetary mixer  
28 (Thinky mixer) at 2000 rpm. DGEBA, DGENG, and curing agent were first mixed together for 1  
29 min, followed by addition of CF. To ensure a good dispersion, the CF was added with an increment  
30 of 10 wt%, each increment was mixed for 1 min. TS720 was then added and mixed for 2 min. The  
31 supporting matrix is composed of silicone oil and 5 wt% of rheology modifier (fumed silica, CAB-  
32 O-SIL M5, Cabot), prepared by mixing in a planetary mixer at 2000 rpm for 2 min.

### 33 34 **2.2 Embedded 3D printing**

35 The as-prepared ink was first loaded into a 15 ml syringe, which was then mounted to the Hyrel  
36 3D printer. All samples were printed using a 620  $\mu\text{m}$  stainless-steel nozzle. The as-prepared  
37 supporting matrix was loaded into containers with various sizes for different printing structures.  
38 The matrix-filled container was placed on the print stage. The printing paths were manually  
39 designed and generated with Gcode. After printing, the matrices with the embedded inks were  
40 heated to 80  $^{\circ}\text{C}$  overnight for complete epoxy curing, followed by the removal and cleaning of the  
41 supporting matrix. To adjust the fiber alignment while maintaining the same beam diameter,  
42 multiple thinner beams with larger rate ratios, offering better fiber alignment, were extruded  
43 together to merge into a single thicker beam that corresponds to a smaller  $R_r$ , yielding worsened

1 fiber alignment. The rate ratio is calculated as  $V_e/V_t$ . The  $V_t$  is determined by recording the time  
2 during which the nozzle travels a fixed distance.  $V_e$  is measured by recording the time during  
3 which a fixed volume of ink is extruded. This volume extrusion rate is then converted into a linear  
4 extrusion rate by dividing the nozzle cross-sectional area.  $V_e$  remains consistent during each  
5 plunger movement, we used the same syringe, nozzle size, and prepared inks and matrices with  
6 the same formulation.

7 The gcode for the embedded 3D printing was prepared by a custom algorithm that generates  
8 toolpaths based on the lattice structure geometry with careful control of extrusion parameters  
9 within standard G-code commands. First, we extract all vertices and struts from the lattice structure.  
10 Before the nozzle moves to a new position, we implement extruder reversal (G1 E-1.5) to create  
11 negative pressure at the nozzle tip. This prevents material from dripping during non-printing  
12 movements. After positioning the nozzle at the start point of a strut, we prime the extruder (G1  
13 E1.5) to ensure consistent material flow when printing begins. The actual printing move (G1  
14 command) includes calculated extrusion amount based on the distance and the selected rate ratio,  
15 which directly controls the fiber alignment. Additionally, we compute the proper 5-axis  
16 coordinates at both the starting and ending points based on each strut's direction vector. At  
17 intersection nodes, we added pause commands (G4) with durations determined from our  
18 experimental data (Figure S3) to ensure proper bonding between struts.

### 19 **2.3 Heat transfer measurement**

20 For each sample, the lattice cubes with identical dimensions and the same beam diameter were  
21 printed for comparison. The printed lattice cubes were placed onto an Aluminum block, which was  
22 heated to a constant temperature of 100 °C. The top and bottom of the lattices were coated with a  
23 thin layer of the corresponding ink to ensure a good contact with the heat source. The temperature  
24 of the lattice top and heating time were recorded by using a IR camera (Hti-Xintai high resolution).

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### 26 **2.4 Mechanical property test**

27 Simple cube lattices (10x10x10 cm) were printed for compression test, and rectangular slabs  
28 (3x12x120 mm) were printed for flexural test. For the simple cubic compression test, the true  
29 modulus of the cubic lattice is adopted, which is computed by dividing the compression force over  
30 the total area of the cross-section of four vertical beams. SC/BCC lattices with a size of 3x3x3 unit  
31 cells were printed at  $\langle 001 \rangle$  and  $\langle 110 \rangle$  orientations for compression tests to obtain the  
32 experimental data for anisotropic ratio calculation. Details are shown in Figure S7. The Poisson's  
33 ratio is calculated under relative density  $\bar{\rho} = 0.1$  by  $\nu = -\frac{\varepsilon_x}{\varepsilon_z}$ , Where  $\varepsilon_x$  is the strain in X axis  
34 and  $\varepsilon_z$  is the strain in Z axis during compression in the  $\langle 001 \rangle$  direction. For  $\langle 001 \rangle$  orientation  
35 compression test, lattice in Fig. S6B was printed. For  $\langle 110 \rangle$  orientation compression test, lattice  
36 structure in Fig. S6D was printed. Both lattices are extracted from the SC/BCC lattice structure  
37 (Fig. S6A, C). The shear modulus is calculated by using the following equations:

$$38 \quad G = \frac{1}{\frac{1}{E_{110}} - \frac{1-\nu}{2E}}$$

1 Where  $\nu$  is the Poisson's ratio during the compression at  $\langle 001 \rangle$  orientation,  $E$  is the Young's  
2 modulus of  $\langle 001 \rangle$  orientation and  $E_{110}$  is the Young's modulus of  $\langle 110 \rangle$  orientation. All tests  
3 were conducted using Instron 5944 universal testing machine (Instron Corporation, Norwood,  
4 MA). The applied loads were measured using the Instron load cell with a load capacity of 2000 N,  
5 while displacements were tracked using the integrated encoder connected to the crosshead  
6 movement.

## 9 **2.5 Fiber alignment characterization**

10 The fiber alignment within the carbon fiber–epoxy composites is measured by SEM (FEI Quanta  
11 3D FEG FIB) and X-ray computed tomography (XRCT). Tomographic images were acquired  
12 using the XCT microscope Zeiss Versa 510 system, set to an optical magnification of 4x, achieving  
13 a spatial resolution of  $\sim 1$  micron. The tomographs were then segmented in the VGStudioMax  
14 2024.1 software using the paint and segment tool. This segmentation process separates the short  
15 carbon fibers from the matrix. To ensure the accuracy of the segmentation, we measured the  
16 statistics of fiber thickness and adjusted the segmentation parameters to improve the gray value  
17 ranges representing the fibers, distinguishing them from the background matrix. This iterative  
18 process continued until the fibers were appropriately segmented. Following segmentation, an  
19 erosion operation of one voxel was applied to marginally disconnect intersecting fibers, preventing  
20 interference with the subsequent analysis of fiber orientation. A reference orientation was defined  
21 along the axial direction aligned with the build direction of the composites (see Fig. S2B). The  
22 orientations of the fibers were then calculated using the Fiber Composite Material Analysis module.  
23 The results for the 3D orientation distribution relative to the axial direction are shown in Fig. 3  
24 and S2, alongside heat maps of the histogram normalized over the total number of short fibers  
25 captured in the analysis.

## 27 **2.6 Numerical analysis of a simple cubic/BCC architected solid**

28 Details described in supporting materials.

## 31 **3. Results**

32 EMB3D printing entails extruding the printing ink into a supporting matrix, in which the embedded  
33 ink is immobilized, preserving its precise placement (Fig. 1A). The existence of the supporting  
34 matrix facilitates nozzle translation of nozzle in all positions, which enables ink deposition in a  
35 three-dimensional space. This distinctive feature allows the printing of highly complex geometries,  
36 for example, an Octet lattice, and a body centered cubic (BCC)/simple cubic (SC) lattice (Fig. 1C).  
37 More importantly, it offers freedom of extrusion path in a 3D context, including Z-axis direction,  
38 offering fiber alignment in all 3D directions. Fig. 1C-i shows a picture of the extrusion paths in x-  
39 y plane, z-axis direction, and diagonal direction. In EMB3D printing, extrusion rate ( $R$ ), the rate  
40 of ink flowing out of the nozzle, and nozzle translation rate ( $r$ ), the speed of the nozzle moving  
41 within the supporting matrix, together determine the fiber orientation. By controlling the printing  
42 parameters, we are able to manage the fiber orientation in highly localized regions, thus producing

1 diverse fiber micro-structures in a single object (Fig. 1B). This paves the way for the fabrication  
2 of metamaterials with programmable properties. For example, Fig. 1D demonstrates the successful  
3 manipulation of a BCC/SC lattice structure's anisotropic nature, generated by varied stiffness of  
4 the  $\langle 110 \rangle$  and  $\langle 001 \rangle$  orientations, achieving either isotropic characteristic or even more extreme  
5 anisotropy (further details in later sections).

### 6 7 **3.1 Matrix elasticity for high-fidelity printing**

8 To enable high resolution EMB3D printing of engineered composites, a crucial requirement is the  
9 structural integrity, ensuring that the embedded structures remain undistorted upon the nozzle  
10 translation. In addition to the appropriate viscosity, compatibility and Herschel-Bulkley behavior  
11 of the ink and matrix (38), optimized printing path has been reported for minimizing the disruptive  
12 nozzle travel motion, albeit it requires sophisticated algorithm calculations and is highly topology  
13 dependent (39), as some disruptive travel is inevitable in many prints. Here we found an additional  
14 criterion for high-fidelity embedded printing, that is a strong solid-like behavior with high elastic  
15 response of the supporting matrix, indicated by a low  $\tan\delta$  (equal to  $G''/G'$ ,  $G''$  is the loss modulus  
16 and  $G'$  is the storage modulus). To investigate this phenomenon, we have prepared different  
17 supporting matrices by mixing silicone oil (serves as matrix fluid) with two silica nanoparticles,  
18 TS720 and M5. While these matrices exhibit overlapping viscosity, yield stress, and storage  
19 modulus, they display a distinctive  $\tan\delta$  (Fig. 2A~2C). M5 matrix has a  $\tan\delta$  of 0.015 before  
20 yielding, one order of magnitude lower than that of all TS720 matrices (value of 0.2), suggesting  
21 a higher elastic response (Fig. 2C). We compared the printing quality in these matrices by printing  
22 test structures (Fig. 2D, cross structure, printing path in Fig. S1; and 2E, pyramid structure;). Both  
23 tests revealed that M5 matrix yields better printing quality. A series of TS720 matrices with  
24 varying particle loadings were prepared. Despite possessing a wide range of viscosities, moduli,  
25 and yield stresses, these TS720 matrices all share a high  $\tan\delta$ . It can be seen that noticeable  
26 distortion of the horizontal lines is observed in all TS720 matrices (Fig. 2D ii), and the two tips of  
27 the pyramid are spatially separated (Fig. 2E ii). On the contrary, the addition of 5 wt% M5 to  
28 silicone oil initiated minimal displacement on the horizontal line (Fig. 2D iii), and the two tips are  
29 completely connected (Fig. 2E iii). As M5 matrix shares overlapping viscosity, yield stress, and  
30 storage modulus with the TS720 matrix (Fig.2A, B), the importance of a much lower  $\tan\delta$  is  
31 highlighted. The distortion of the embedded ink can occur even without direct contact with the  
32 nozzle, as the surrounding matrix yields under the stress field induced by the translating nozzle.  
33 The stronger elastic response of the M5 matrix leads to a more rapid stress drop from the nozzle  
34 compared to the TS720 matrices, offering minimal yielding of the matrix for less ink displacement.  
35 As such, we establish the role of matrix elasticity as an additional criterion for high-feature fidelity  
36 of embedded printing, irrespective of printing path and Herschel-Bulkley behavior.

### 37 38 39 **3.2 Controlling fiber 3D alignment while maintaining EMB3D printing integrity**

40 The optimized EMB3D printing allows the three-dimensional ink extrusion for fiber 3D alignment.  
41 The alignment is achieved through the shear fields generated from the combined effects of ink  
42 extrusion rate ( $R$ ) and nozzle translation rate ( $r$ ). We can control fiber orientation by modulating  
43 the rate ratio ( $R_r$ ) of  $R$  (set at 5 mm/s) and  $r$ , from highly random ( $R_r = 6$ ) to highly aligned ( $R_r =$   
44 1). The control can be realized in a 3D space, as illustrated by the multiple extruded beams in  
45 various directions, including the through-plane direction (Fig. S2A). SEM images (Fig. 3A, D, and  
46 Fig. S2C, D) illustrate the fiber arrangement in beams printed with different  $R_r$ . The fiber

1 topologies exhibit identical alignment at the same  $R_r$ , regardless of the extrusion directions,  
2 demonstrating simultaneous fiber alignment in both through-plane and in-plane directions. We  
3 also used X-ray microcomputed tomography ( $\mu$ XCT) for quantitative analysis. The alignment is  
4 characterized by the angle  $\theta$  between the CF and the beam axial direction (Fig. S2B), the values  
5 of which are indicated by different colors. We introduce "alignment efficiency," denoting the  
6 proportion of CFs with  $\theta < 45^\circ$ . Clearly, the beams with  $R_r = 1$  comprise predominantly blue/green  
7 fibers that are parallel to the axial direction, giving a 79.4% alignment efficiency and a peak  
8 distribution at  $15^\circ$  (Fig. 3B, C). As a comparison, a notable presence of red fibers (perpendicular  
9 to axial direction) is observed at  $R_r = 4$  with only 39.0% alignment efficiency and a peak  
10 distribution at  $50^\circ$  (Fig. 3E, F). The fiber alignment of other  $R_r$  was also measured (Fig. 3G, Fig.  
11 S3) which follows the trend that higher  $R_r$  leads to higher peak angle and lower alignment  
12 efficiency. The worsened fiber alignment at higher  $R_r$  is due to the over-extrusion when ink exits  
13 the nozzle faster than the nozzle translation in the matrix. This disrupts the axial shear field for  
14 fiber alignment, as the ink tends to have outward flow directions.  
15 On the other hand, the outward flow enlarges the beam diameter, as excess ink is pushed outward  
16 for lateral expansion (Fig. 3G). Beam diameter affects the EMB3D printing quality, as thicker  
17 beams generate stronger connection at the beam nodes. Fig. 3H shows the quantitatively analyzed  
18 result of the connection strength from a testing "cross" shape. The beams fail to be chemically  
19 bonded, indicated by the normalized force  $< 1$ , when  $R_r$  drops below 1.75 (more details discussed  
20 in supporting information). Consequently, lowering  $R_r$  yields better alignment, but compromises  
21 the printing fidelity. To address this, we implemented pausing time at the node for extra ink  
22 extrusion at lower  $R_r$ . The connection strength of each  $R_r$  with pausing time from 0s to 1s was  
23 examined (Fig. S4), and the data provides valuable guidance for selecting printing parameters  
24 when modulating  $R_r$  to control fiber alignment.

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### 27 **3.3 Three-dimensional property enhancement**

28 The three-dimensional fiber alignment in our EMB3D-printed composites gives rise to property  
29 enhancement across all directions, especially for the through-plane directions, a longstanding  
30 challenge of the existing engineered composites (40, 41). Here we examined the stiffness and heat  
31 dissipation, as they are crucial for many composite applications. Both tests confirm the significant  
32 property enhancement in complete three-dimensional directions. The through-plane heat transfer  
33 was tested by placing printed lattices on top of a heating source ( $100^\circ\text{C}$ ) and the temperature  
34 change of the top of the lattices was monitored by using an infrared (IR) camera (Fig. 4A). We  
35 compared the performance of composites of pure epoxy, epoxy with random CF (epoxy-rCF,  
36 printed at  $R_r = 4$ ), and aligned CF (epoxy-aCF, printed at  $R_r = 1$ ), of which the fiber arrangement  
37 was confirmed by  $\mu$ XCT (Fig. 4B). The results (Fig. 4C, Fig. S5) illustrate that the vertically  
38 aligned CFs generate the highest maximum temperature and fastest heating rate, indicating the  
39 most substantial enhancement of heat transfer in Z-axis direction, which is noticeably better than  
40 random CF. This is attributed to the sequence of straight head-to-tail connections of aligned CF  
41 offering the shortest path for heat flux in the vertical direction compared to that offered by random  
42 fibers. Using the same sample compositions, we printed simple cubes and flexural bars at various  
43 orientations ( $0^\circ$ ,  $45^\circ$  and  $90^\circ$ ) and measured their compressive and bending stiffness (Fig. 4D). It  
44 is evident that when the CF is properly aligned, the Young's modulus and flexural modulus  
45 increased 45.7% and 55.6% from random fiber, respectively, while the ultimate strain remains  
46 nearly unchanged (Fig. 4D, Fig. S6). This significant enhancement in stiffness is realized solely

1 from internal fiber arrangement control by modulating the  $R_r$ , without any changes to external  
2 architecture or material structure/composition. Furthermore, nearly identical stress-strain curves  
3 are observed from samples with the same fiber alignment but printed at different orientations ( $0^\circ$ ,  
4  $45^\circ$  and  $90^\circ$ ) in both compression and flexural tests. The isotropic mechanical performance  
5 signifies the achievement of simultaneous stiffness enhancement in both in-plane and through-  
6 plane directions induced by the 3D fiber alignment.

### 8 **3.4 Metamaterial composite lattice with programmable elastic anisotropy**

9 Engineered materials with tunable properties are highly sought after as they suit diverse  
10 requirements, such as directional reinforcing characteristics in aerospace and automotive industries  
11 (42–44). The above demonstrated ability to change the mechanical behavior by tuning the fiber  
12 arrangement enables our EMB3D printing to produce engineered composites with programmable  
13 anisotropic ratios and directional stiffness with the same 3D architecture. This can be achieved  
14 simply by modulating the rate ratio ( $R_r$ ) at specific regions within the 3D lattice layout. Here we  
15 use the hybrid unit cell as an example. The cell is comprised of two sub-cells with distinct  
16 symmetries, namely simple cubic (SC) and body centered cubic (BCC) subunit cells, which  
17 together show an anisotropic stiffness tensor (Fig. 5A, B). By combining the experimental data  
18 and numerical calculations (Fig. 5C), we demonstrated that designing the fiber alignment within  
19 these two-symmetry groups allows us to program the stiffness anisotropy ratios of the unit cells,  
20 spanning from highly anisotropic to isotropic behavior. As shown in Fig. 5A, we have printed  
21 lattice cubes composed of four distinct SC/BCC designs and coded the fiber orientation as “a”  
22 (aligned CF) and “r” (random CF): 1) SC and BCC with aligned CF (abbreviated as SC-a/BCC-a),  
23 2) SC and BCC with random CF (SC-r/BCC-r), 3) SC with aligned CF, BCC with random CF  
24 (SC-a/BCC-r), 4) SC with random CF, BCC with aligned CF (SC-r/BCC-a). Each design has been  
25 experimentally tested and numerically calculated at the  $\langle 001 \rangle$  and  $\langle 110 \rangle$  directions (Fig. 5B,  
26 details in supporting information, Fig. S7, 8). In the polar graph, we used azimuthal coordinate to  
27 represent the load direction, and the radial coordinate for the Young’s modulus, which increases  
28 outward radially. The distinct anisotropies of the different designs can be visualized in “orientation  
29 spheres”, with the cut plane through the sphere representing the polar plot (Fig. 5D). Numerical  
30 and experimental data show excellent agreement, confirming the accuracy of the numerical design  
31 and predictions. The stiffness anisotropy of the metamaterial was quantitatively examined by  
32 effective anisotropic ratio,  $A$  (45):

$$A = \frac{2(1+\nu)G}{E}$$

35 Where  $\nu$  is the Poisson’s ratio during the compression at  $\langle 001 \rangle$  orientation,  $E$  is the Young’s  
36 modulus of  $\langle 001 \rangle$  orientation, and  $G$  is the shear modulus of  $\langle 001 \rangle$  orientation (see supplemental  
37 information). The samples with original structure, including SC-a/BCC-a and SC-r/BCC-r exhibit  
38 an anisotropic ratio of 1.5 (Fig. S9, 10), consistent with the known anisotropic nature of the  
39 SC/BCC lattice (46). We converted this anisotropic nature to isotropic behavior by designing the  
40 SC-a/BCC-r structure, which shows an identical modulus at all orientations. On the other hand,  
41 the anisotropic ratio of the original structure is increased to 2.5 when SC-r/BCC-a design is applied.  
42 Again, the capability of changing the anisotropic ratio and directional moduli of a given lattice is  
43 solely achieved by varying meso-scale fiber arrangement, while the composites have identical  
44 lattice topology, material composition, and density.

1  
2 **4. Discussion**

3 We have developed an EMB3D printing method for carbon fiber/epoxy composites, enabling  
4 simultaneous through-plane and in-plane fiber alignment. This approach has led to significant  
5 enhancements in mechanical properties and thermal conductivity in a three-dimensional context.  
6 It also generates engineered composites with programmable stiffness anisotropy and directional  
7 moduli. Our formulations of ink and supporting matrix incorporate optimized rheological  
8 properties to ensure high printing resolution for complex lattice architectures with meso-scale 3D  
9 alignment. Additionally, we have demonstrated the ability to adjust fiber alignment at specific  
10 regions by varying the rate ratio during printing, enabling precise control over localized micro-  
11 structures. By integrating regional fiber orientation with macro-architectural design, we have  
12 achieved the fabrication of 3D metamaterial lattices, effectively converting its anisotropic nature  
13 to isotropic behavior. An expanded degree of freedom of local fiber orientation control within the  
14 3D matrices can be achieved by expanding the kinematics of nozzle movement to a 5-axis system.  
15 Furthermore, a multi-nozzle system can be incorporated to parallelize the extrusion process and  
16 print multiple struts at once in a single motion system. This study paves the way to control  
17 structural behaviors via synergistic control of meso-scale alignment and 3D macro-architectures,  
18 which opens new opportunities to manage conflicting material properties for multiple applications.

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27 J.Y.P., performed research; Q.C., S.S.S., S.Z., A.J.D.S., analyzed data; and Q.C., S.S.S., S.Z.;  
28 A.J.D.S., S.K., N.S.H., H.H. V.S.D. and X.Z. wrote the paper.

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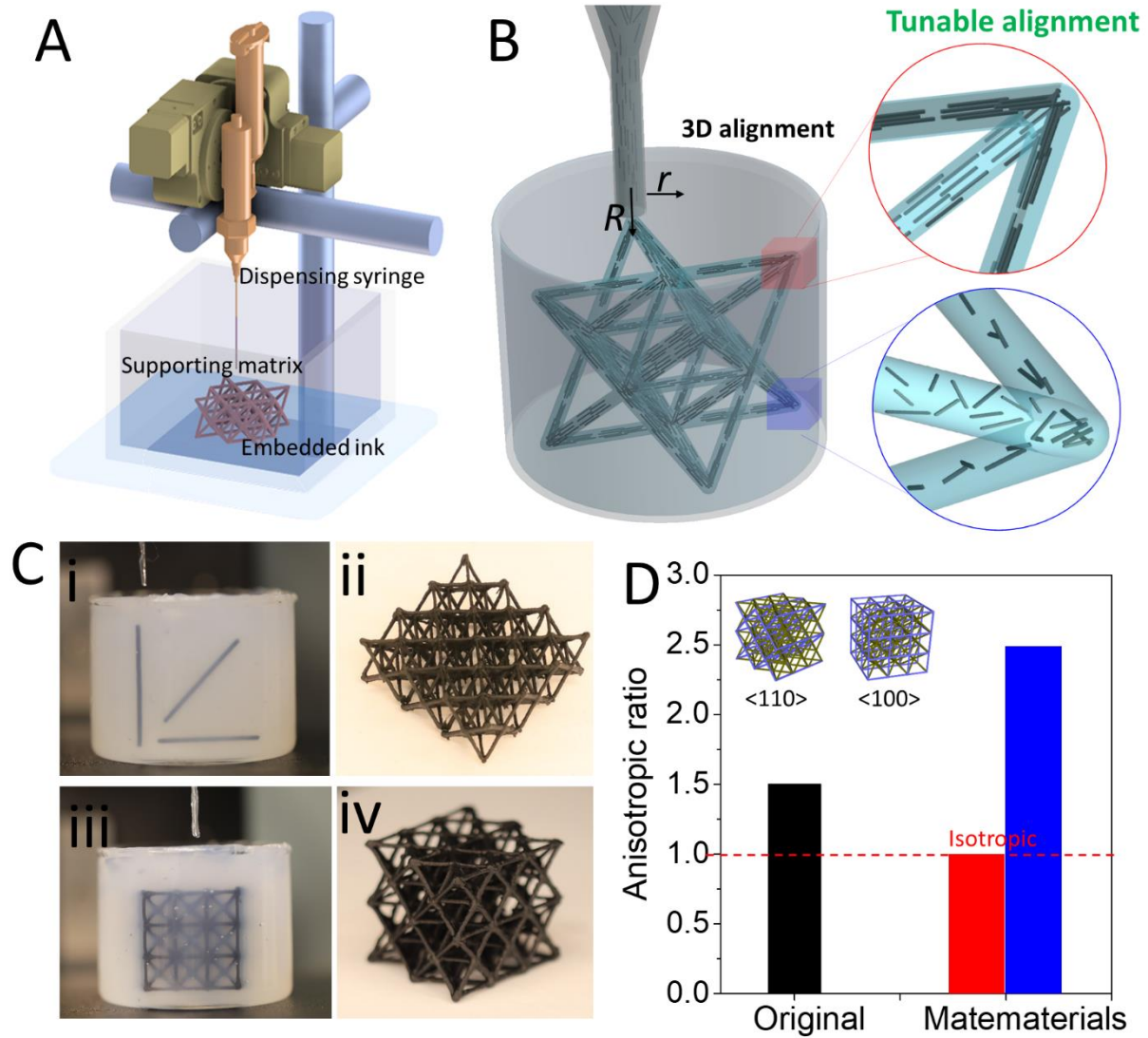
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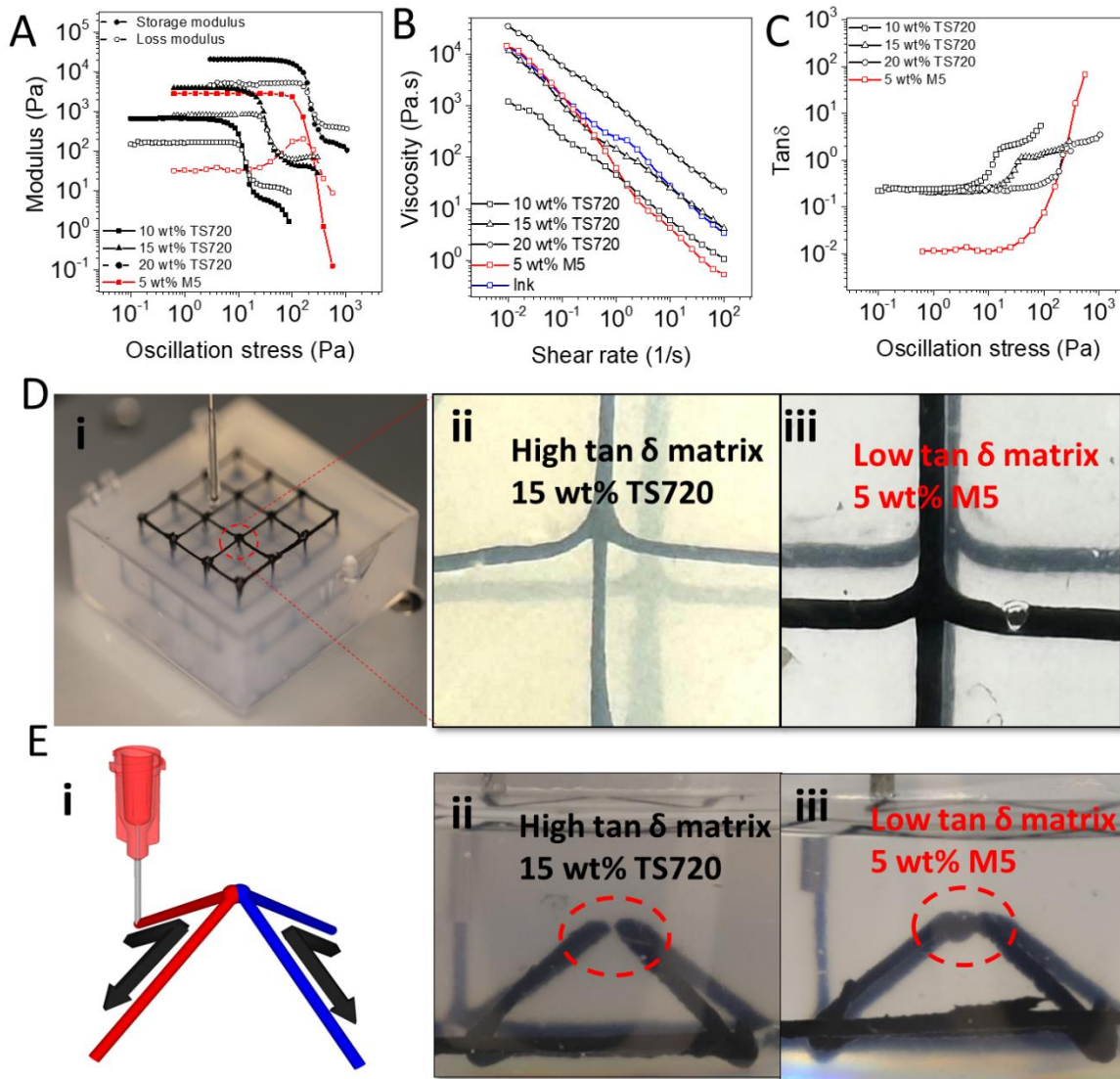
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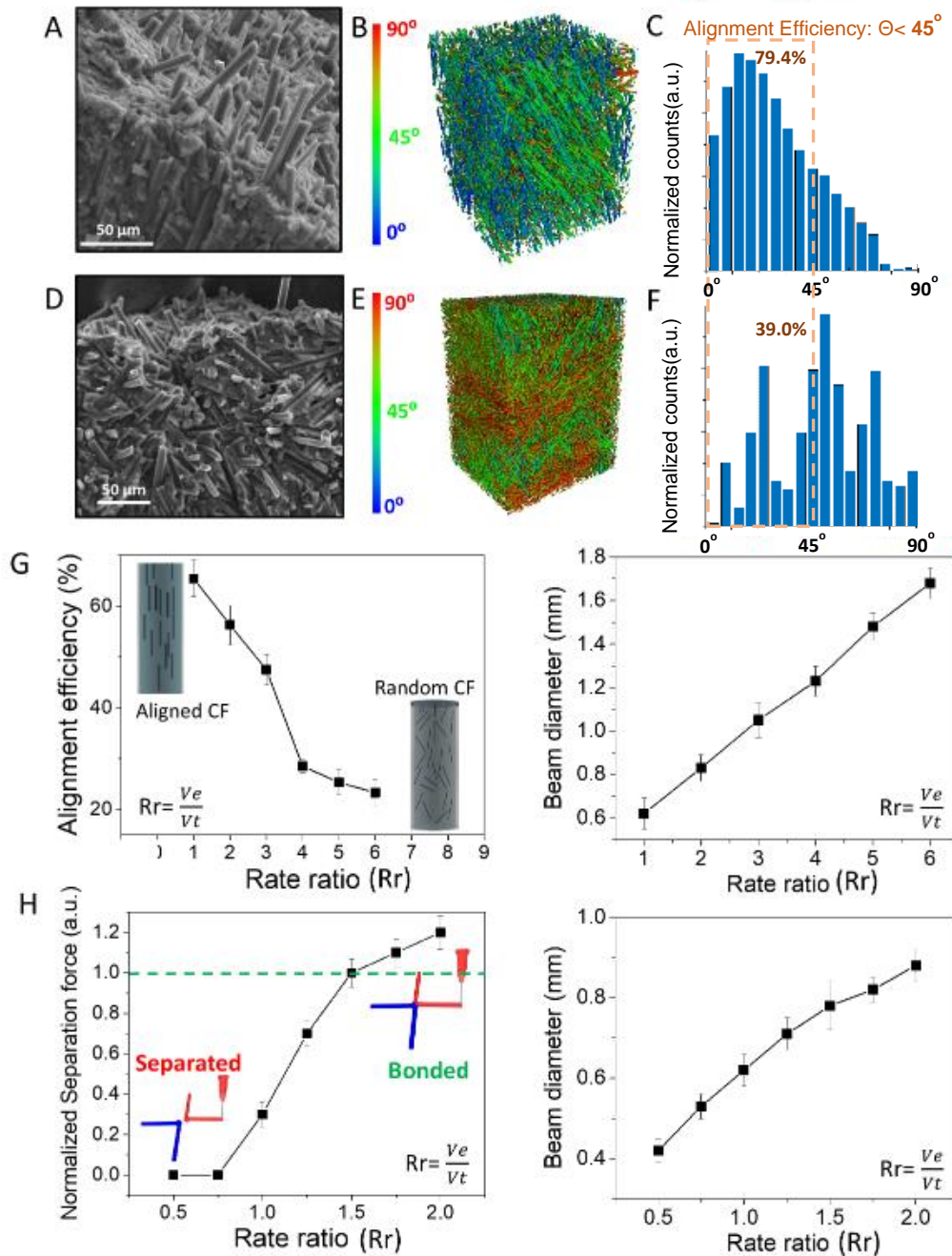
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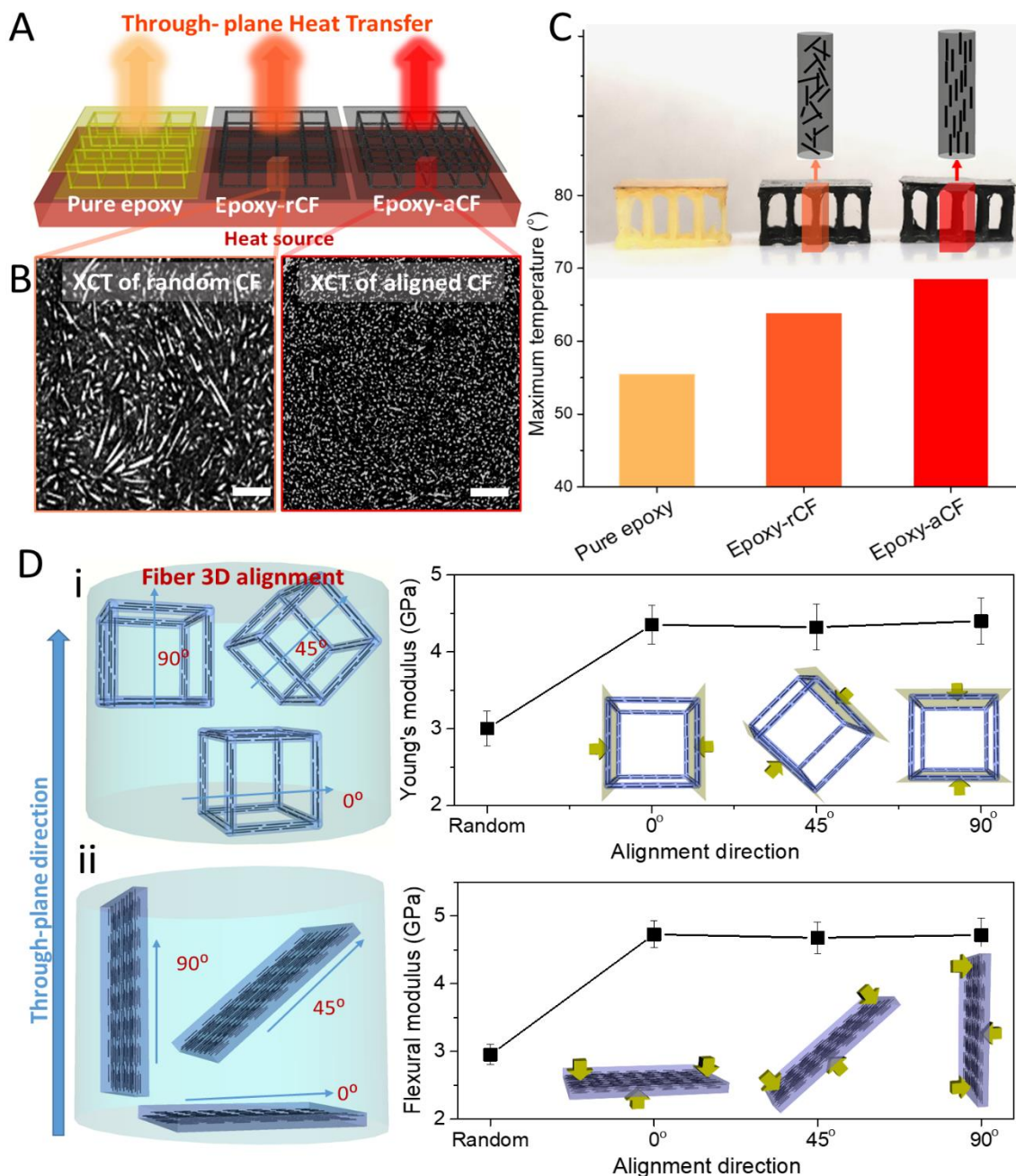
**Fig. 1. Embedded 3D printing with 3D fiber alignment.** A) Schematic of EMB3D printing process. B) Illustration of controlled carbon fiber 3D alignment at specific regions. C) Images of different EMB3D printed structures. i) extrusion of ink in x-y plane, along z-axis, and diagonal direction. ii) Octet lattice; iii) completed printing of BCC/SC lattice; iv)  $\langle 110 \rangle$  orientation of BCC/SC lattice. D) Manipulation of anisotropic ratio of lattice structure by varying fiber alignment in a 3D context. Insert:  $\langle 110 \rangle$  and  $\langle 001 \rangle$  orientation of the BCC/SC lattice.



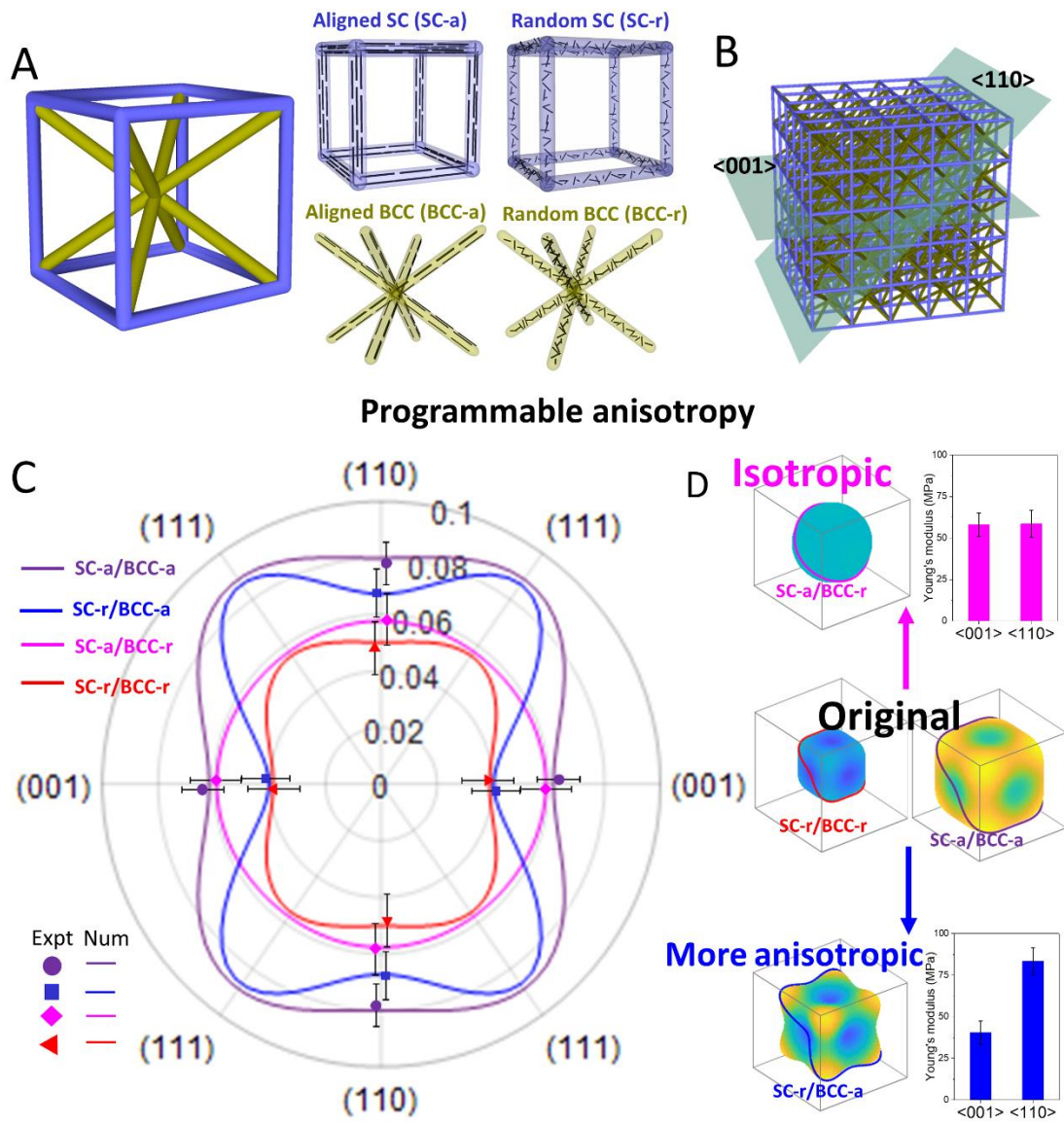
**Fig. 2. Optimized matrix rheology with high elastic response for high-fidelity EMB3D printing.** A) Log-log plot of the storage modulus,  $G'$ , and loss modulus,  $G''$ , as a function of shear stress for matrices prepared with different fumed silica nanoparticles. B) Viscosity as a function of shear stress of different matrix compositions. C)  $\text{Tan}\delta$  as a function of shear stress of different matrix compositions. D) Optical images of the printed “cross” structures for printing quality illustration. (i) completed printing of “cross” structure, (ii) structure printed in matrix with high  $\text{tan}\delta$  (TS720 matrices) and (iii) structure printed in matrix with low  $\text{tan}\delta$  (M5 matrix). E) Optical images of the printed pyramid structure for the printing quality illustration. (i) colored printing path, (ii) structure printed in TS720 matrices and (iii) structure printed in



**Fig. 3. Controlling fiber 3D alignment and maintaining printing quality by tuning rate ratio of extrusion rate and nozzle translation rate.** A)-C): Samples extruded by rate ratio =1 at  $\theta = 90^\circ$ , D)-F): Samples extruded by rate ratio = 4 at  $\theta = 90^\circ$ . A, D) SEM images of cross-sections of extruded beams. B, E) Reconstructed models with angle distribution of  $\mu\text{XCT}$  scan results. C, F) angle distribution plots of aligned CFs. G) Beam size and alignment efficiency at different rate ratios. Inset: fiber alignment illustration. H) Beam size and the separation force at different rate ratios. Inset: printing bath of the “cross”



**Fig. 4. Three-dimensional properties enhancement by 3D fiber alignment.** A) Illustration of heat transfer measurement. B)  $\mu$ XCT images of top-view cross-section of vertical beams with random and aligned carbon fibers. C) Optical images of samples of pure epoxy, epoxy-rCF, epoxy-aCF, and their corresponding maximum temperatures after heat transfer. D) Mechanical tests of samples printed at various directions in a 3D space. i) Compression test of simple cubes with varying fiber alignment directions. ii) Flexural test of flexural specimens with varying fiber alignment directions.



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**Fig. 5. Programmable anisotropy via tuning regional fiber 3D alignment.** A) Schematic of the unit lattice cell composed of simple cubic (SC) and body centered cubic (BCC) subcells, each subcell with distinct random and aligned fiber designs. B) Schematics of the  $\langle 001 \rangle$  and  $\langle 110 \rangle$  orientations. C) Polar graph of numeric predictions and experimental data: Young's modulus as function of the orientation of the compression with respect to the unit cell lattice vectors. D) Modulating the stiffness anisotropic ratio by varying the fiber 3D alignment. Within the cube frame representing the edges of unit cell, shaped solids indicate the directional value of Young's modulus in radial distance from the cube center and in color. Color indicates value from most compliant (blue) to stiffest (yellow). All cubes share the same color axis.

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